



GPS Module DataSheet

Name: Ultra High Sensitivity and The Smart Antenna GPS Module

Model NO.: SKM58

Revision: 001

Revision History:

Revision	Description	Approved	Date
001	Initial Release to 001	Neil	20110101

Skylab M&C Technology Co., Ltd.

Address: Room.801, Bldg.211, Terra Industrial Park, Futian District, Shenzhen

Phone: 86-755 8340 8210 (Sales Support)

Phone: 86-755 8340 8130 (Technical Support)

Fax: 86-755-8340 8560

E-Mail: sales@skylab.com.cn

©Copyright 2011 SkyLab M&C Co., Ltd, All Right Reserved

The information contained herein is subject to change without notice.

SkyNav SKM58 Series

Ultra High Sensitivity and Low Power

The Smart Antenna GPS Module



General Description

The SkyNav SKM58 Series with embedded GPS antenna enables high performance navigation in the most stringent applications and solid fix even in harsh GPS visibility environments.

It is based on the high performance features of the MediaTek 3329 single-chip architecture, Its -165dBm tracking sensitivity extends positioning coverage into place like urban canyons and dense foliage environment where the GPS was not possible before. The 6-pin UART connector design is the easiest and convenient solution to be embedded in a portable device and receiver like PND, GPS mouse, car holder, personal locator, speed camera detector and vehicle locator.

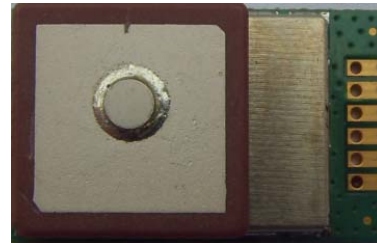


Figure 1: SKM58 Top View

Applications

- LBS (Location Based Service)
- Vehicle navigation system
- PND (Portable Navigation Device)
- GPS mouse and Bluetooth GPS receiver
- Timing application

Features

- Ultra high sensitivity: -165dBm
- 22 tracking/66 acquisition-channel receiver
- WAAS/EGNOS/MSAS/GAGAN support
- AGPS support
- NMEA protocols (default speed: 9600bps)
- One serial port
- Embedded patch antenna $12*12*4\text{ mm}$
- Operating temperature range: $-40\text{ to }85^\circ\text{C}$
- RoHS compliant (Lead-free)
- Tiny form factor : $20.5\text{mm} \times 12.8\text{mm} \times 7.8\text{mm}$

Pin Assignment

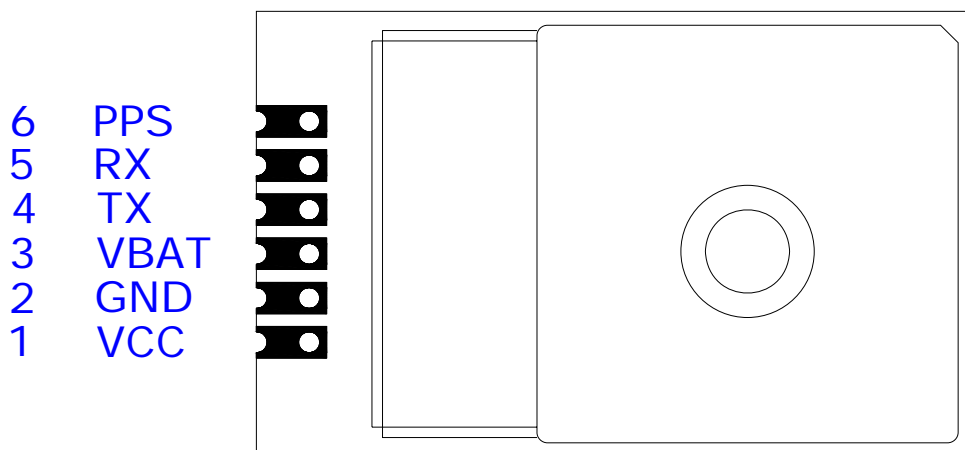


Figure 2: SKM58 Pin Package

Performance Specification

Parameter	Specification	
GPS receiver		
Receiver Type	L1 frequency band, C/A code, 22 Tracking / 66 Acquisition-Channel	
Sensitivity	Tracking Acquisition	-165dBm -148dBm
Accuracy	Position Velocity Timing (PPS)	3.0m CEP50 without SA(Typical Open Sky) 0.1m/s without SA 60ns RMS
Acquisition Time	Cold Start Warm Start Hot Start Re-Acquisition	36s 33s 1s <1s
Power Consumption	Tracking Acquisition Sleep/Standby	40mA @3.3V Typical 45mA @3.3V TBD
Navigation Data Update Rate	1Hz	
Operational Limits	Altitude Velocity Acceleration	Max 18,000m Max 515m/s Less than 4g
Antenna Specifications		
Outline Dimension	12 x 12 x 4.0 mm	
Center Frequency	1575 ± 3 MHz	
Bandwidth	10 MHz min	
Impedance	50 Ω	
Axial Ratio	3 dB max	
Polarization	RHCP	
Mechanical requirements		
Dimension	20.5mm x12.8mm x 7.8mm	
Weight	6g	
Power consumption		
VCC	3.0~4.2V	
Current	45mA(typical)	
Environment		
Operating temperature	-40 ~ +85°C	
Storage temperature	-40 ~ +125°C	
Humidity	≅95%	

Hardware Interfaces Configuration

Power Supply: Regulated power for the SKM58 series is required. The input voltage V_{cc} should be 3.0V~4.2V, current is no less than 150mA. Suitable decoupling must be provided by external decoupling circuitry(10uF and 1uF). It can reduce the Noise from power supply and increase power stability.

UART Ports: The module supports one full duplex serial channels UART. The serial connections are at

2.85V LVTTTL logic levels, if need different voltage levels, use appropriate level shifters. the data format is however fixed: X, N, 8, 1, i.e. X baud rate, no parity, eight data bits and one stop bit, no other data formats are supported, LSB is sent first. The modules default baud rate is set up 9600bps. The RXD0 & TXD0 recommended to pull up (10KΩ). It can increase the stability of serial data.

Pin Description

Pin No.	Pin name	I/O	Description	Remark
UART Port				
1	VCC	P	Module Power Supply	VCC: 3.0~4.2V
2	GND	G	Module Power Ground	Reference Ground
3	VBAT	O	RTC and backup SRAM power (2.0-4.2V)	May be connect to Battery
4	TXD	O	TTL: $3.1V \geq V_{OH} \geq 2.4V$ $-0.3V \leq V_{OL} \leq 0.4V$	Strap pin, default MUST pull up
5	RXD	I	TTL: $3.6V \geq V_{IH} \geq 2.0V$ $-0.3V \leq V_{IL} \leq 0.8V$	Leave Open if not used
6	PPS	O	Time pulse Signal (Default 100ms pulse/sec)	Leave Open if not used

Mechanical Specification

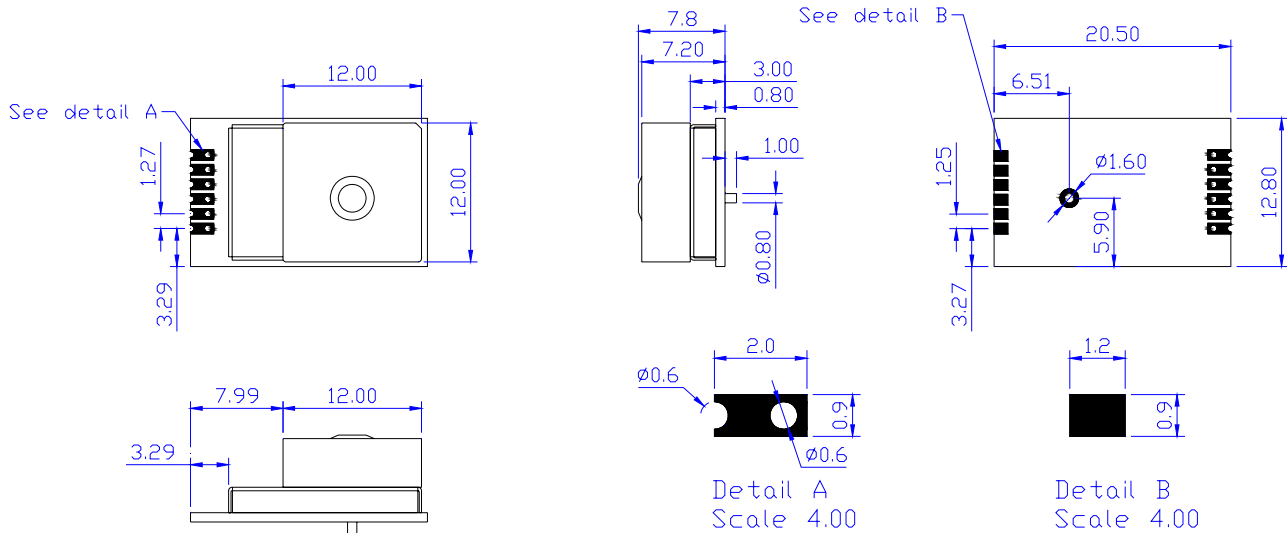


Figure 3: SKM58 Series Dimensions

Software Protocol

NMEA 0183 Protocol

The NMEA protocol is an ASCII-based protocol. Records start with a \$ and with carriage return/line feed. GPS specific messages all start with \$GPxxx where xxx is a three-letter identifier of the message data that follows. NMEA messages have a checksum, which allows detection of corrupted data transfers.

The SkyNav SKG12A supports the following NMEA-0183 messages: GGA, GLL, GSA, GSV, RMC, VTG, ZDA. The module default NMEA-0183 output is set up GGA, GSA, RMC, GSV, and default baud rate is set up 9600bps.

Table 1: NMEA-0183 Output Messages

NMEA Record	Description	Default
GGA	Global positioning system fixed data	Y
GLL	Geographic position—latitude/longitude	N
GSA	GNSS DOP and active satellites	Y
GSV	GNSS satellites in view	Y
RMC	Recommended minimum specific GNSS data	Y
VTG	Course over ground and ground speed	N
ZDA	Date and Time	N

GGA-Global Positioning System Fixed Data

This sentence contains the position, time and quality of the navigation fix.

See RMC for Fix Status, Fix Mode, Fix Date, Speed, and True Course.

See GSA for Fix Type, PDOP, and VDOP.

\$GPGGA,021514.000,2232.1799,N,11401.1823,E,1,6,1.25,84.0,M,-2.2,M,,*74

Table 2: GGA Data Format

Name	Example	Units	Description
Message ID	\$GPGGA		GGA protocol header
UTC Position	021514.000		hhmmss.sss
Latitude	2232.1799		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	11401.1823		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Position Fix Indicator	1		See Table 2-1
Satellites Used	6		Range 0 to 12
HDOP	1.25		Horizontal Dilution of Precision
MSL Altitude	84.0	meters	Altitude (referenced to the Ellipsoid)
AltUnit	M	meters	Altitude Unit
GeoSep	-2.2	meters	Geoidal Separation
GeoSepUnit	M	meters	Geoidal Separation Unit
Age of Diff.Corr.	<Null>	second	Null fields when it is not Used

Diff.Ref.Station ID	<Null>		Null fields when it is not Used
Checksum	*74		
EOL	<CR> <LF>		End of message termination

Table 2-1: Position Fix Indicators

Value	Description
0	Fix not available or invalid
1	GPS SPS Mode, fix valid
2	Differential GPS, SPS Mode, fix valid
3	GPS PPS Mode, fix valid

GLL-Geographic Position – Latitude/Longitude

This sentence contains the fix latitude and longitude.

```
$GPGLL,2232.1799,N,11401.1824,E,021513.000,A,A*50
```

Table 3: GLL Data Format

Name	Example	Units	Description
Message ID	\$GPGLL		GLL protocol header
Latitude	2232.1799		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	11401.1824		dddmm.mmmm
E/W Indicator	E		E=east or W=west
UTC Position	021513.000		hhmmss.sss
Fix Status	A		A=data valid or V=data not valid
Fix Mode	A		A=autonomous, N = No fix, D=DGPS, E=DR
Checksum	*50		
EOL	<CR> <LF>		End of message termination

GSA-GNSS DOP and Active Satellites

This sentence contains the mode of operation, type of fix, PRNs of the satellites used in the solution as well as PDOP, HDOP and VDOP.

```
$GPGSA,A,3,26,05,18,15,27,29,,,,,,1.52,1.25,0.87*0F
```

Table 4: GSA Data Format

Name	Example	Units	Description
Message	\$GPGSA		GSA protocol header
Mode 1	A		See Table 4-2
Mode 2	3		See Table 4-1
ID of satellite used	26		Sv on Channel 1
ID of satellite used	05		Sv on Channel 2
...
ID of satellite used	<Null>		Sv on Channel 12 (Null fields when it is not Used)
PDOP	1.52		Position Dilution of Precision

HDOP	1.25		Horizontal Dilution of Precision
VDOP	0.87		Vertical Dilution of Precision
Checksum	*0F		
EOL	<CR> <LF>		End of message termination

Table 4-1: Mode 1

Value	Description
1	Fix not available
2	2D Fix
3	3D Fix

Table 4-2: Mode 2

Value	Description
M	Manual-forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

GSV-GNSS Satellites in View

This sentence contains the PRNs, azimuth, elevation, and signal strength of all satellites in view.

\$GPGSV,3,1,12,15,79,333,42,42,50,127,,29,45,263,44,02,36,124,30*7E

\$GPGSV,3,2,12,26,36,226,34,05,35,046,22,27,33,161,29,21,16,319,*7D

\$GPGSV,3,3,12,10,15,066,31,18,14,285,45,24,12,319,15,08,09,047,18*7E

Table 5: GSV Data Format

Name	Example	Units	Description
Message ID	\$GPGSV		GSV protocol header
Number of Message	3		Total number of GSV sentences (Range 1 to 3)
Message Number	1		Sentence number of the total (Range 1 to 3)
Satellites in View	12		Number of satellites in view
Satellite ID	15		Channel 1(Range 01 to 32)
Elevation	79	degrees	Channel 1(Range 00 to 90)
Azimuth	333	degrees	Channel 1(Range 000 to 359)
SNR(C/NO)	42	dB-Hz	Channel 1(Range 00 to 99, null when not tracking)
...			...
Satellite ID	02		Channel 4(Range 01 to 32)
Elevation	36	degrees	Channel 4(Range 00 to 90)
Azimuth	124	degrees	Channel 4(Range 000 to 359)
SNR(C/NO)	30	dB-Hz	Channel 4(Range 00 to 99, null when not tracking)
Checksum	*7E		
EOL	<CR> <LF>		End of message termination

Depending on the number of satellites tracked multiple messages of GSV data may be required.

RMC-Recommended Minimum Specific GNSS Data

This sentence contains the recommended minimum fix information.

See GGA for Fix Quality, Sats Used, HDOP, Altitude, Geoidal Separation, and DGPS data.

See GSA for Fix Type, PDOP and VDOP.

\$GPRMC,023345.000,A,2232.1767,N,11401.1953,E,0.18,151.55,100410,,A*6B

Table 6: RMC Data Format

Name	Example	Units	Description
Message ID	\$GPRMC		RMC protocol header
UTS Position	023345.000		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	2232.1767		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	11401.1953		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Speed Over Ground	0.18	Knots	
Course Over Ground	151.55	Degrees	True Course
Date(UTC)	100410		ddmmyy
Magnetic variation	<Null>	Degrees	Null fields when it is not Used
Magnetic Variation Direction	<Null>		E=east or W=west (Null fields when it is not Used)
Fix Mode	A		A=autonomous, N = No fix, D=DGPS, E=DR
Checksum	*6B		
EOL	<CR> <LF>		End of message termination

VTG-Course Over Ground and Ground Speed

This sentence contains the course and speed of the navigation solution.

\$GPVTG,148.81,T,,M,0.13,N,0.24,K,A*3D

Table 7: VTG Data Format

Name	Example	Units	Description
Message ID	\$GPVTG		VTG protocol header
Tcourse	148.81	Degrees	True Course
Reference	T		T = True
Mcourse	<Null>	Degrees	Magnetic Course (Null fields when it is not Used)
Reference	M		M = Magnetic (Null fields when it is not Used)
Speed over ground	0.13	Knots	Nautical Miles per Hour
Units	N		Knots
Speed over ground	0.24	Km/hr	in Kilometers per Hour
Units	K		Kilometer per hour
Mode	A		A=Autonomous, N=No fix, D=DGPS, E=DR
Checksum	*3D		
EOL	<CR> <LF>		End of message termination

ZDA-Date and Time

This sentence contains UTC date & time, and local time zone offset information.

\$GPZDA,023345.000,10,04,2010,,*50

Table 8: ZDA Data Format

Name	Example	Units	Description
Message ID	\$GPZDA		ZDA protocol header
UTC Time	023345.000		hhmmss.sss
Day	10		UTC time: day (01 ... 31) dd
Month	04		UTC time: month (01 ... 12) mm
Year	2010		UTC time: year (4 digit year) yyyy
local zone hours	<null>		Local Time Zone Offset Hours (Null fields when it is not Used)
local zone minutes	<null>		Local Time Zone Offset Minutes (Null fields when it is not Used)
Checksum	*50		
EOL	<CR> <LF>		End of message termination